

Low Power Low Drag (LPLD) conformance monitoring





Introduction

- Low Power Low Drag (LPLD) is an established aircraft noise abatement technique introduced by ICAO as far back as 1970
- It describes the lowest noise configuration for a given speed and/or altitude during approach
- Drag from deployed landing gear causes turbulence which creates noise heard on the ground
- Airframe noise dominates aircraft noise on arrival



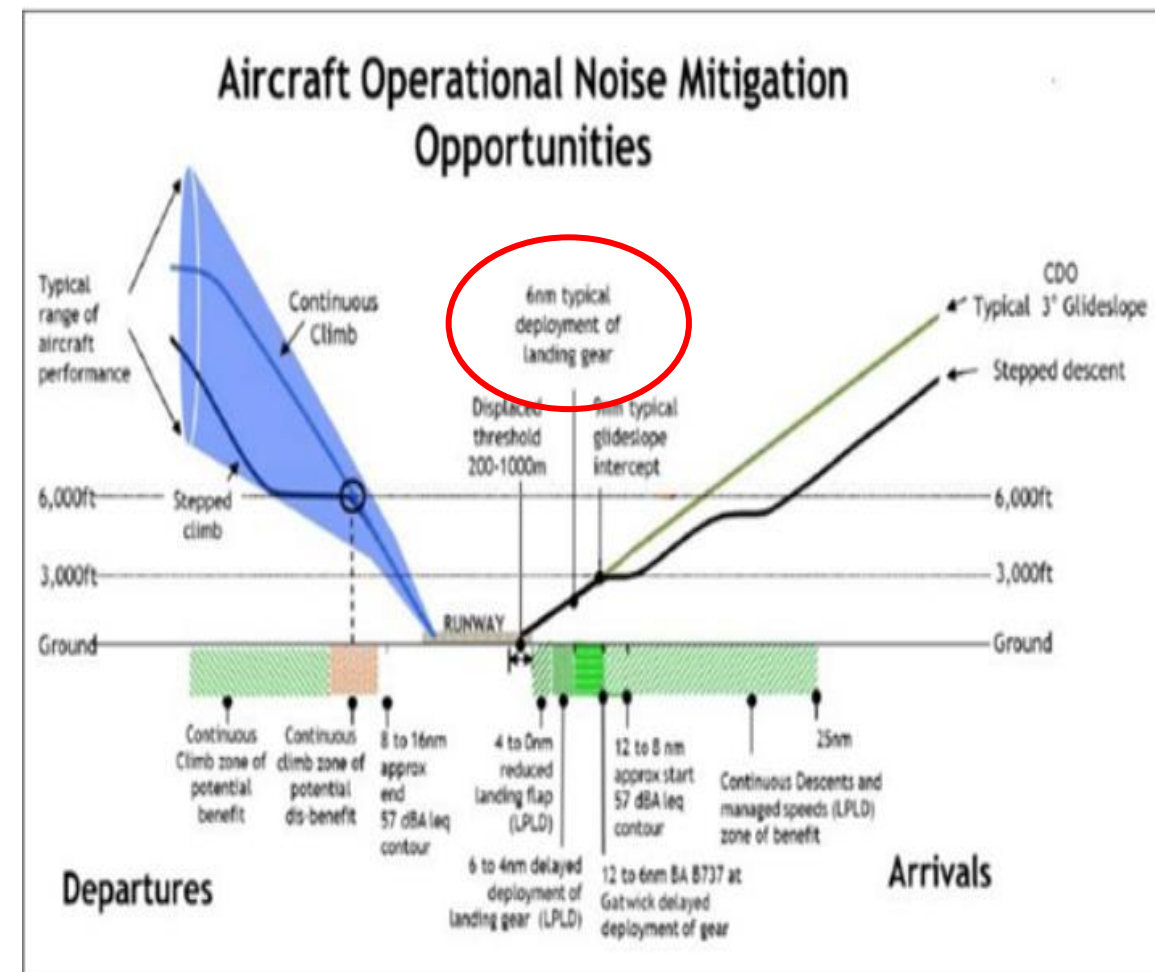
Image credit: NASA's Ames Research Center, Patrick Moran; NASA's Langley Research Center, Mehdi Khorrami; Exa Corporation, Ehab Fares



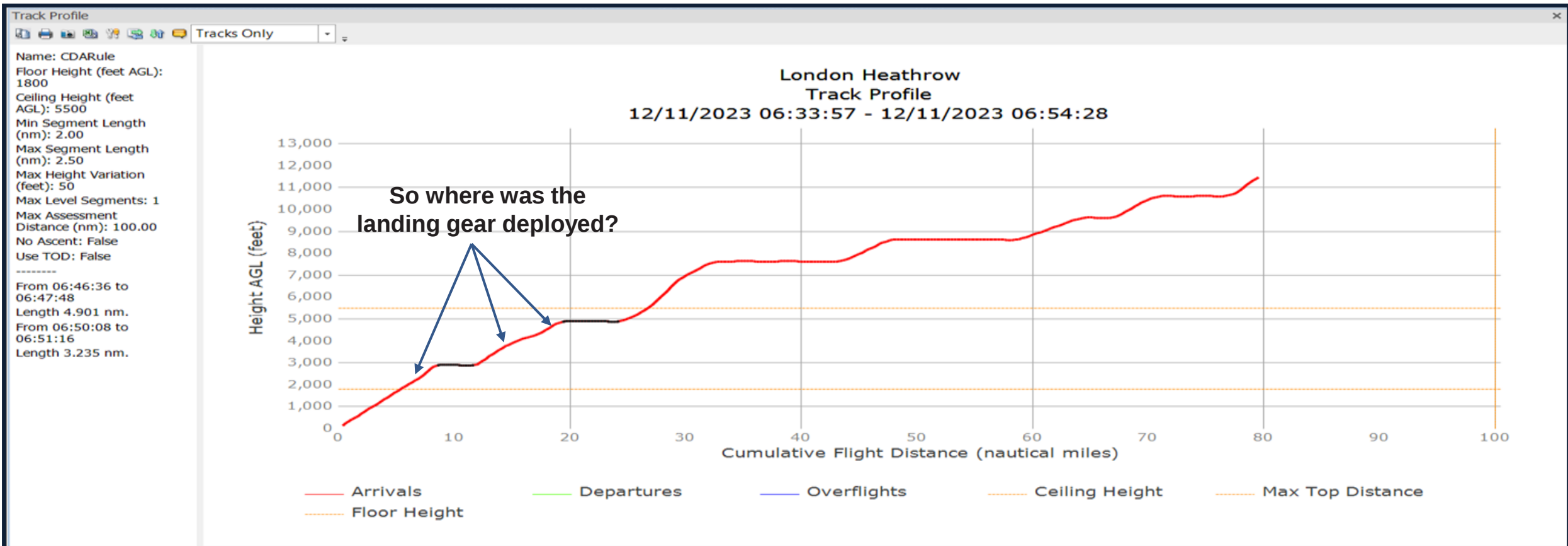
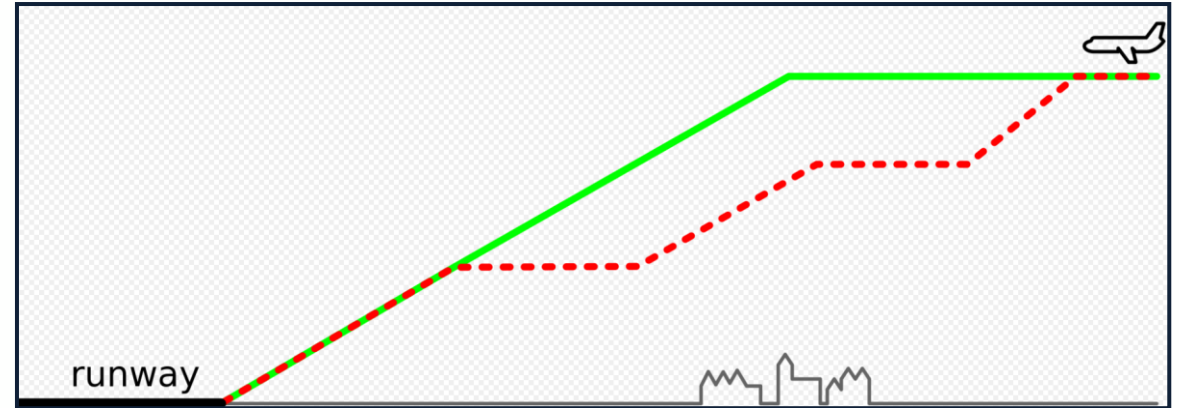
Where does the requirement for LPLD come from?

ICAO - Continuous Descent Operations (CDO) Manual (Doc 9931)

ICAO Document 9931, the 'Continuous Descent Operations Manual', CDO is defined as “an aircraft operating technique aided by appropriate airspace and procedure design and appropriate ATC clearances enabling the execution of a flight profile optimized to the operating capability of the aircraft, with low engine thrust settings and, where possible, **a low drag configuration**, thereby reducing noise, fuel burn and emissions during descent. The optimum vertical profile takes the form of a continuously descending path, with a minimum of level flight segments only as needed to decelerate and configure the aircraft or to establish on a landing guidance system (e.g. ILS).”



Continuous Descent Arrival & LPLD Procedures.



Past LPLD studies have been purely visual, linked to ANOMS

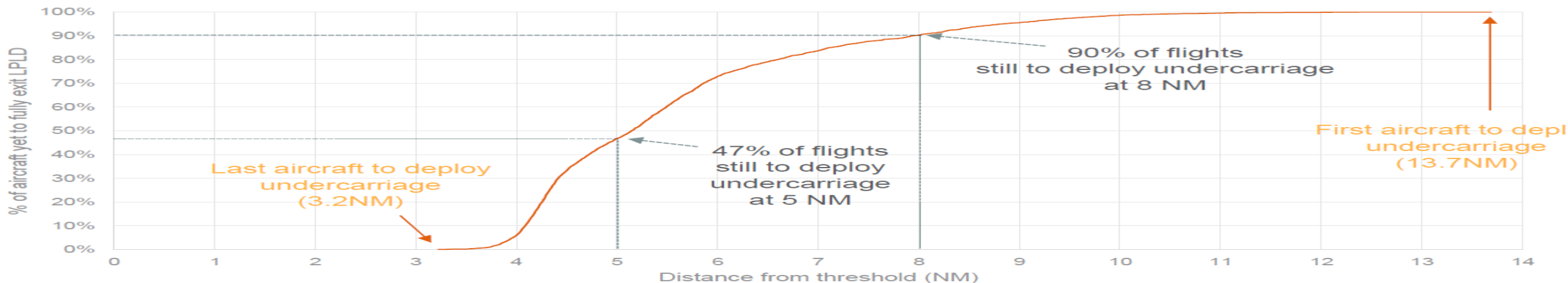
Quotes: “The integrity of wheels down measurements were investigated by comparing observed overhead times with ANOMS gate penetration times”

Comparatively lower accuracy for 09L has been attributed to the observation location being **offset by ~1,000 metres from the approach** – made the ‘overhead’ time more difficult to judge

Accuracy for 27L/27R may have been influenced by the observers judgement of when an aircraft was directly overhead



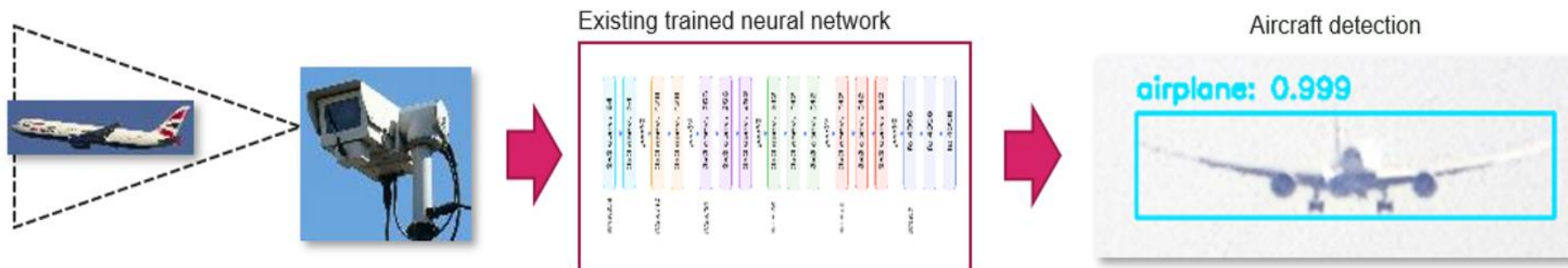
Cumulative distribution for aircraft yet to fully exit LPLD configuration versus distance from threshold





Automation.

STEP 1 – DETECTION OF DESIRED TARGETS IN IMAGERY



STEP 2 – PROCESSING OF IMAGES FOR GEAR

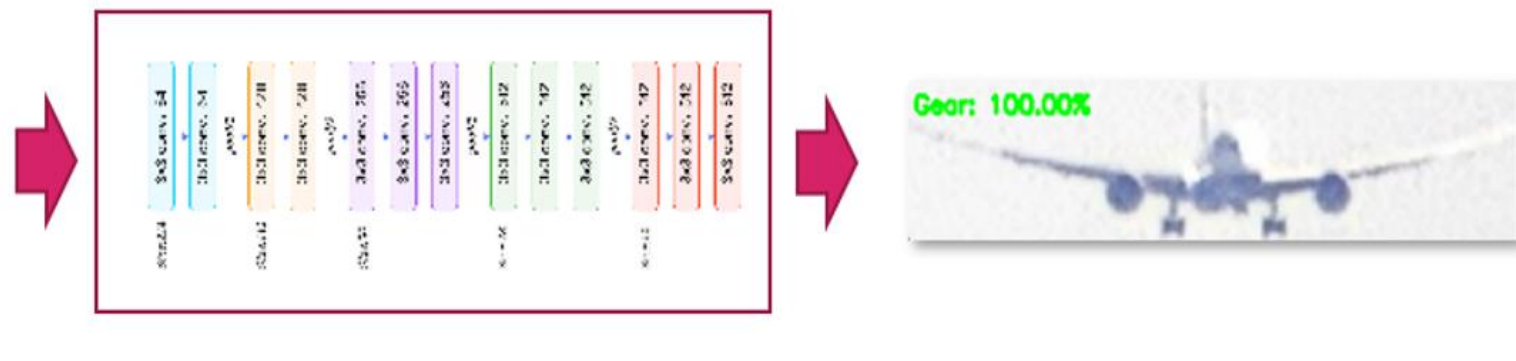
No Gear



Gear



Re-training of existing neural network





Example results.



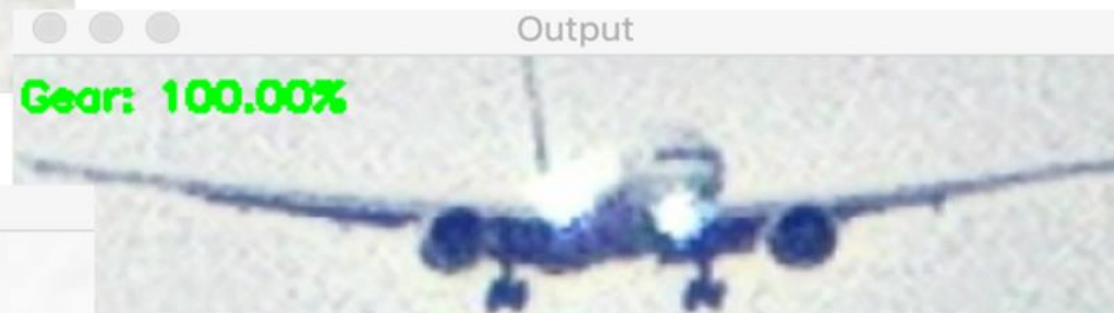


Example results.





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Next steps.

- With the technology now available the opportunity to monitor LPLD presents itself.
- Requirement is for better cameras sited in pairs for each approach.
- Retrain the algorithms which have improved hugely since 2019.
- ANOMS Development work to accept the data and allow it to be reported.

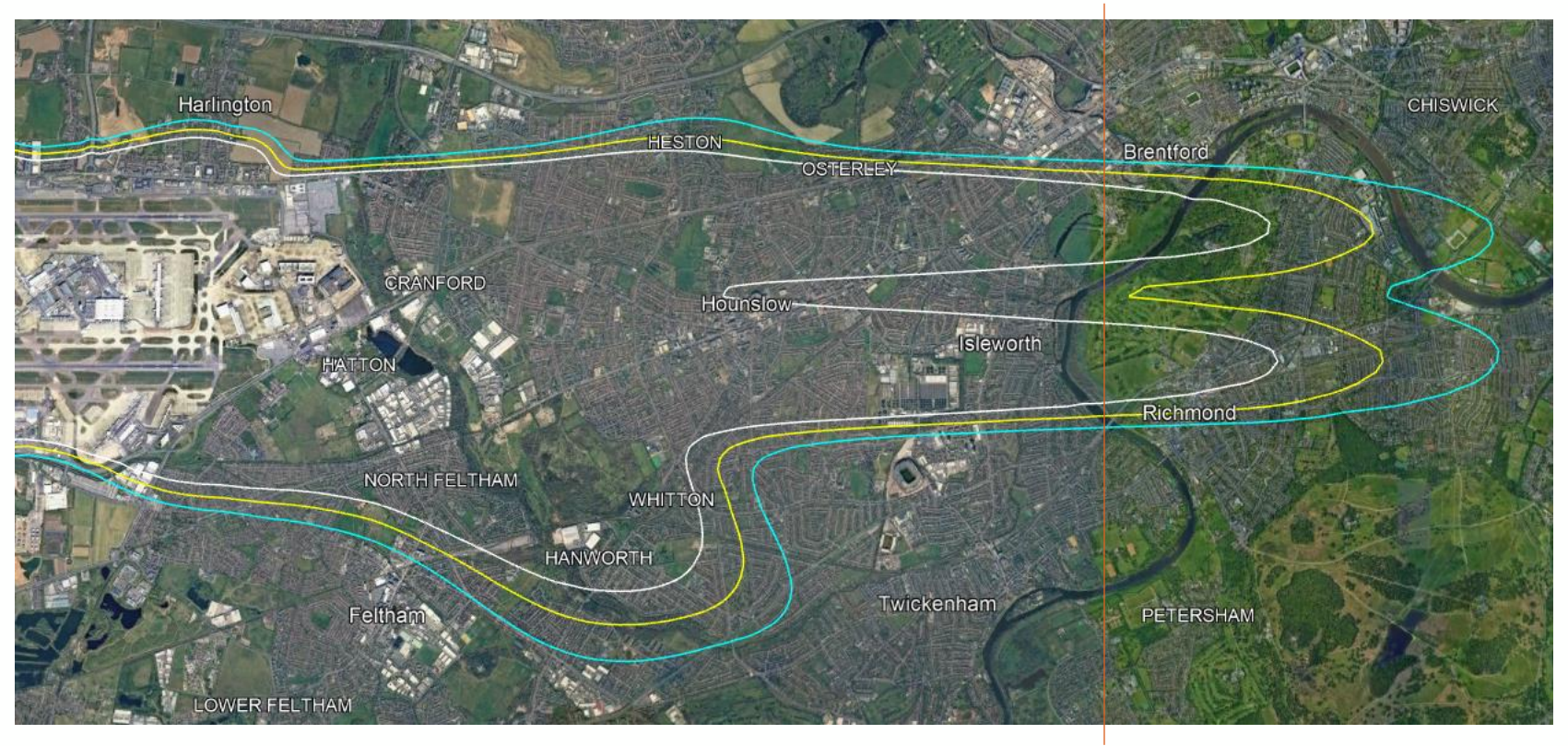
Benefits.

- Reputational benefit for airports.
- Research from UK CAA says an individual aircraft event can be reduced by 3-5dB.
- Every 1dB reduction in noise equates to approximately a 20% reduction in the arrivals contour.

What does that benefit mean?

- Land gear *could* be deployed by 5nm from threshold

LHR 55,56 & 57dB daytime noise contours



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